



robots ready for work





## Machine vision for quality control and closed-loop robot operation

## Camera

Focus: 3.8 mm
Field of view: 70 degrees
Range: 15 cm - infinity
Distortion: <1%

lmage-scan resolution and speed: 2592 x 1936 7 fps

1920 x 1080 12 fps 1280 x 720 32 fps



## Inputs & Outputs

Input:

5V 2A power input SNAP pin

service port (serial)

Output:

STATUS pin OK pin NG pin

**HDMI** 

USB:

for installing detection algorithm & downloading images

## Simply plug in

to collect images to install algorithm to start production to maintain

- 1) connect to WiFi or insert an empty USB drive 2) start scanning 3) upload images
- 1) download algo.so file 2) wait for new algorithm to be installed
- 1) monitor output pins 2) start scanning
- 1) download NOWING maintenance file 2) wait for status indicator 3) unplug USB drive

